



Modeling Hubbert curves as MIP formulation in TIMES

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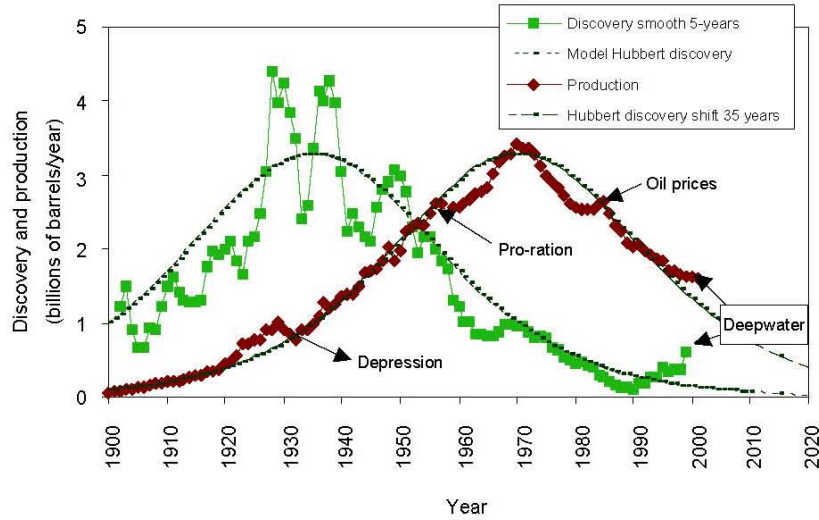


Overview

- Introduction to Hubbert curves
- Approximation of Hubbert curves using Mixed Integer Programming:
 - i. Logistic Hubbert curves
 - ii. Big-M formulation
 - iii. Convex hull formulation
- Preliminary example results



Hubbert curve (USA, 48 states)



Source: Laherrère, 2003



Hubbert curves

„Discoveries self-regulate discoveries“

$$\frac{\partial CD(t)}{\partial t} \propto \underbrace{CD(t)}_{\text{Learning effect}} \cdot \underbrace{(Q_\infty - CD(t))}_{\text{Depletion effect}}$$

$CD(t)$: Cumulative discoveries

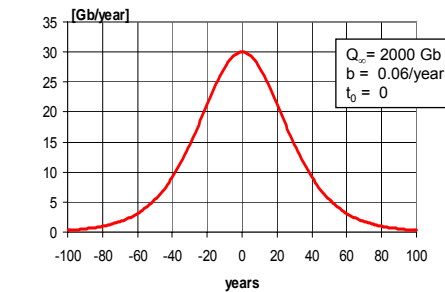
Q_∞ : Oil-in-place

Discoveries follow a **Hubbert curve**



Production follows a **Hubbert curve**

$$x_{t,k} = \frac{URR_k \cdot b_k \cdot e^{-b_k(t-t_{0,k})}}{(1 + e^{-b_k(t-t_{0,k})})^2}$$



$x_{t,k}$: Production of category k

URR_k : Ultimate recoverable resource category k

b_k : Steepness parameter k

$t_{0,k}$: Peak year



Logistic Hubbert curves as MIP

$$x_t = q_t \cdot b \cdot \left(1 - \frac{q_t}{URR}\right) \quad \text{Relationship for Hubbert curve}$$

Piece-wise linear approximation of non-convex function

$$x_t = \lambda_{0,t} X_0 + \lambda_{1,t} X_1 + \lambda_{2,t} X_2 + \lambda_{3,t} X_3 + \lambda_{4,t} X_4 + \lambda_{5,t} X_5$$

$$q_t = \lambda_{0,t} Q_0 + \lambda_{1,t} Q_1 + \lambda_{2,t} Q_2 + \lambda_{3,t} Q_3 + \lambda_{4,t} Q_4 + \lambda_{5,t} Q_5$$

$$\lambda_{0,t} + \lambda_{1,t} + \lambda_{2,t} + \lambda_{3,t} + \lambda_{4,t} + \lambda_{5,t} = 1$$

Piece-wise linear approximation

$$q_t = \sum_{\tau=1}^t x_\tau$$

$$\lambda_{0,t} \leq y_{0,t}$$

$$\lambda_{1,t} \leq y_{0,t} + y_{1,t}$$

$$\lambda_{2,t} \leq y_{1,t} + y_{2,t}$$

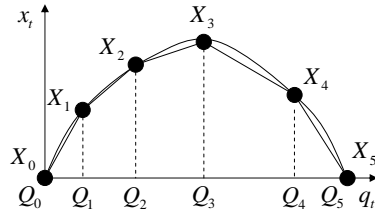
$$\lambda_{3,t} \leq y_{2,t} + y_{3,t}$$

$$\lambda_{4,t} \leq y_{3,t} + y_{4,t}$$

$$\lambda_{5,t} \leq y_{4,t}$$

$$y_{0,t} + y_{1,t} + y_{2,t} + y_{3,t} + y_{4,t} + y_{5,t} = 1$$

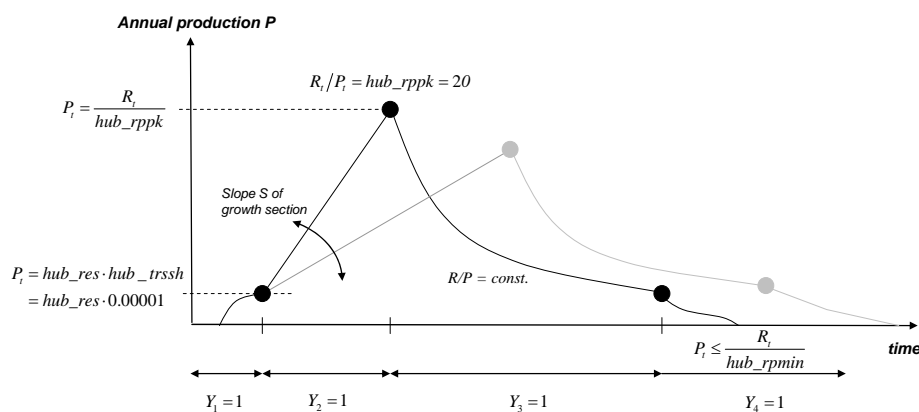
Ensuring only two neighboring points are selected



- x_t Annual production in t
- q_t Cumulative production until t
- $\lambda_{i,t}$ Weighting factor of point i of approximated curve valid in period t
- $y_{i,t}$ Binary variable to ensure only neighboring points are chosen
- i Set of points
- t Time periods
- X_i, Q_i Selected points used to approximate Hubbert curve



Simplified approach for production profiles



- Four sections of curve; Peak specified by minimum resource to production ratio
- Piece-wise linear sections described as disjunctive constraints using Mixed-Integer Programming



Approximation: Big-M method

Disjunctive constraints

$$A_1x \leq b_1 \quad \vee \quad A_2x \leq b_2 \quad \vee \quad A_3x \leq b_3 \quad \vee \quad A_4x \leq b_4$$

„Big M“ Formulation

$$A_1x_1 \leq b_1 + M_1 \cdot (1 - y_1)$$

$$A_2x_2 \leq b_2 + M_2 \cdot (1 - y_2)$$

$$A_3x_3 \leq b_3 + M_3 \cdot (1 - y_3)$$

$$A_4x_4 \leq b_4 + M_4 \cdot (1 - y_4)$$

$$y_1 + y_2 + y_3 + y_4 = 1$$

$$y_1, y_2, y_3, y_4 \in \{0, 1\}$$

$$x \geq 0$$

Advantage: Few constraints

Disadvantage: Loose LP relaxation



Approximation: Convex hull formulation

Disjunctive constraints

$$A_1x \leq b_1 \quad \vee \quad A_2x \leq b_2 \quad \vee \quad A_3x \leq b_3 \quad \vee \quad A_4x \leq b_4$$

„Convex hull“ Formulation

$$A_1z_1 \leq b_1y_1 \quad A_2z_2 \leq b_2y_2 \quad A_3z_3 \leq b_3y_3 \quad A_4z_4 \leq b_4y_4$$

$$0 \leq z_1 \leq U_1y_1 \quad 0 \leq z_2 \leq U_2y_2 \quad 0 \leq z_3 \leq U_3y_3 \quad 0 \leq z_4 \leq U_4y_4$$

$$x = z_1 + z_2 + z_3 + z_4$$

$$y_1 + y_2 + y_3 + y_4 = 1$$

$$y_1, y_2, y_3, y_4 \in \{0, 1\}$$

$$z_1, z_2, z_3, z_4 \geq 0$$

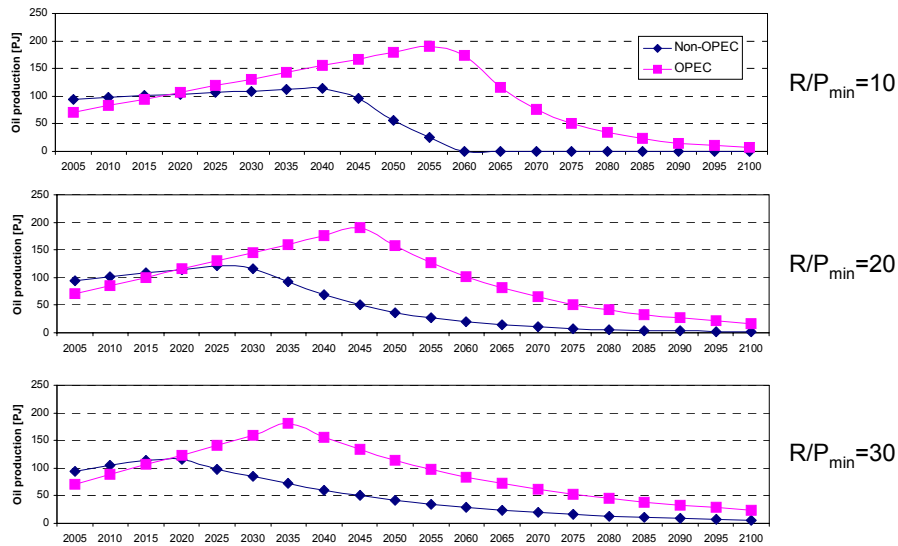
$$x \geq 0$$

Advantage: Tight LP relaxation

Disadvantage: More variables and constraints



Example: Hubbert curves in the TIAM model



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Hubbert as MIP formulation

15. Februar 2007

9



Conclusions

- MIP representation of Hubbert curves as convex hull formulation operational in larger models.
- Critical factor in terms of computation time is the number of Hubbert curves, i.e., binary variables.
- Individual Hubbert curves for different regions and cost categories may require different types of approximations.

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Hubbert as MIP formulation

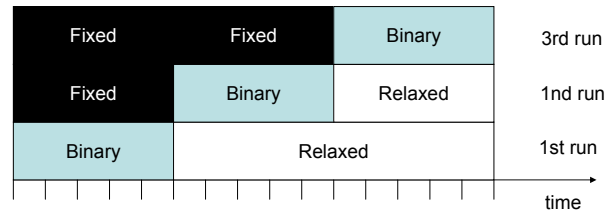
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10



Notes on MIP in TIMES

- Block-wise capacity extension using a Rolling Horizon approach to solve larger models or more integer variables:



- Solver tolerances and options critical for results, to loose tolerances may lead to different solutions.